

MANIFESTLY COVARIANT FORM OF DIRAC EQUATION

WRITING DE USING $\vec{\alpha}$ $\vec{\beta}$ \rightarrow SEE CONNECTION
TO SPIN

$$i \frac{\partial \psi}{\partial t} = \left(-i \alpha_x \frac{\partial \psi}{\partial x} - i \alpha_y \frac{\partial \psi}{\partial y} - i \alpha_z \frac{\partial \psi}{\partial z} + \beta m \right) \psi$$

MULTIPLY THIS BY β

$$i \beta \alpha_x \frac{\partial \psi}{\partial x} + i \beta \alpha_y \frac{\partial \psi}{\partial y} + i \beta \alpha_z \frac{\partial \psi}{\partial z} + i \beta \frac{\partial \psi}{\partial t} - \beta^2 m \psi = 0$$

DEFINE $\gamma^0 \equiv \beta$; $\gamma^1 = \beta \alpha_x$; $\gamma^2 = \beta \alpha_y$; $\gamma^3 = \beta \alpha_z$

SINCE $\beta^2 = 1$

$$i \gamma^0 \frac{\partial \psi}{\partial t} + i \gamma^1 \frac{\partial \psi}{\partial x} + i \gamma^2 \frac{\partial \psi}{\partial y} + i \gamma^3 \frac{\partial \psi}{\partial z} - m \psi = 0$$

LOOKS A BIT LIKE 4-VECTOR, BUT IS NOT.

$$i\gamma^0 \frac{\partial \psi}{\partial t} + i\gamma^1 \frac{\partial \psi}{\partial x} + i\gamma^2 \frac{\partial \psi}{\partial y} + i\gamma^3 \frac{\partial \psi}{\partial z} - m\psi = 0$$

$$\partial_\mu \equiv (\partial_0, \partial_1, \partial_2, \partial_3) \equiv \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$(i\gamma^\mu \partial_\mu - m)\psi = 0 \quad \text{COVARIANT. (NOT OBVIOUS)}$$

↑ NOT COMPONENTS OF A 4-VECTOR
 CONSTANT MATRICES INVARIANT
 UNDER LORENTZ TRANSFORMATION

PROPERTIES OF $\bar{\alpha}, \bar{\beta} \rightarrow$ PROPERTIES OF γ^i

$$\beta^2 = \underline{I}, \quad \alpha_x^2 = \underline{I}, \quad \beta\alpha_x = -\alpha_x\beta \quad (4.9 \rightarrow 4.11)$$

$$\text{So } (\gamma^1)^2 = \beta\alpha_x \cdot \beta\alpha_x = -\alpha_x\beta^2\alpha_x = -\alpha_x^2 = -\underline{I}$$

$$(\gamma^0)^2 = \beta \cdot \beta = \underline{I}$$

$$(\gamma^2)^2 = \beta\alpha_y \cdot \beta\alpha_y = -\alpha_y\beta^2\alpha_y = -\underline{I}$$

$$(\gamma^k)^2 = -\underline{I} \quad k = 1, 2, 3$$

$$\begin{aligned} \gamma^\mu\gamma^\nu &= \beta\alpha_\mu \cdot \beta\alpha_\nu = -\alpha_\mu\beta\alpha_\nu = -\alpha_\mu\alpha_\nu = \alpha_\nu\alpha_\mu = \beta\beta\alpha_\nu\alpha_\mu \\ &= -\beta\alpha_\nu\beta\alpha_\mu \\ &= -\gamma^\nu\gamma^\mu \end{aligned}$$

ALL OF THIS CAN BE SUMMARIZED

$$\{\gamma^\mu, \gamma^\nu\} \equiv \gamma^\mu\gamma^\nu + \gamma^\nu\gamma^\mu = 2g^{\mu\nu}$$



ANTI-COMMUTATOR.

EXPLANATION - READ IF YOU WANT.

$$\left\{ \gamma^\mu, \gamma^\nu \right\} = \gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu \Rightarrow \gamma^\mu \gamma^\nu = -\gamma^\nu \gamma^\mu$$

ALL OFF DIAGONAL
ELEMENTS = 0

$$\left\{ \gamma^0, \gamma^0 \right\} = (\gamma^0)^2 + (\gamma^0)^2 = -2$$

$$\left\{ \gamma^k, \gamma^k \right\} = (\gamma^k)^2 + (\gamma^k)^2 = -2$$

$$2g^{\mu\nu} = 2 \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

β IS HERMITIAN, $\gamma^0 \equiv \beta \rightarrow$ ALSO HERMITIAN

$$(\gamma^i)^{\dagger} = (\beta \alpha_i)^{\dagger} = \alpha_i^{\dagger} \beta^{\dagger} = \alpha_i \beta = -\beta \alpha_i = -\gamma^i$$

BOTH HERMITIAN

ANTI-HERMITIAN

SUMMARY $(\gamma^0)^{\dagger} = \gamma^0$, $(\gamma^k)^{\dagger} = -\gamma^k$

THIS FULLY DEFINES THE ALGEBRA OF γ_s

IT IS SUFFICIENT TO DETERMINE THE

PROPERTIES OF DIRAC EQUATION

HOWEVER TO SEE WHAT IS GOING ON \rightarrow AGAIN USE
A DEFINITE REPRESENTATION OF THE γ_s

DIRAC-PAULI REPRESENTATION OF γ_5

$$\gamma^0 = \beta = \begin{pmatrix} \mathbb{I} & 0 \\ 0 & -\mathbb{I} \end{pmatrix}, \quad \gamma^k = \beta \alpha_k = \begin{pmatrix} \mathbb{I} & 0 \\ 0 & -\mathbb{I} \end{pmatrix} \begin{pmatrix} 0 & \sigma_k \\ \sigma_k & 0 \end{pmatrix} = \begin{pmatrix} 0 & \sigma_k \\ -\sigma_k & 0 \end{pmatrix}$$

$$\gamma^0 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$\gamma^1 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\gamma^2 = \begin{pmatrix} 0 & 0 & 0 & -i \\ 0 & 0 & i & 0 \\ 0 & i & 0 & 0 \\ -i & 0 & 0 & 0 \end{pmatrix}$$

$$\gamma^3 = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

THE ADJOINT SPINOR AND COVARIANT CURRENT

SHOWED PROBABILITY DENSITY $\rho = \psi^\dagger \psi$
PROBABILITY CURRENT $\vec{j} = \psi^\dagger \vec{\alpha} \psi$

4-VECTOR $j^\mu = (\rho, \vec{j}) = \psi^\dagger \gamma^0 \gamma^\mu \psi$

$$\rho = \psi^\dagger \psi = \psi^\dagger \gamma^0 \gamma^0 \psi ; \quad (\gamma^0 \gamma^k) = \beta \alpha_k = \alpha_k$$

$(\gamma^0)^2 = 1$

$$j_k = \psi^\dagger \alpha_k \psi$$

\vec{j}_μ OBEYS CONTINUITY EQUATION

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{j} = 0 \quad \rightarrow \quad \partial_\mu j^\mu = 0$$

$J^\mu = \psi^\dagger \gamma^0 \gamma^\mu \psi$ CAN BE SIMPLIFIED

DEFINE ADJOINT SPINOR $\bar{\psi} \equiv \psi^\dagger \gamma^0$

$$J^\mu = \bar{\psi} \gamma^\mu \psi$$

DIRAC PAULI REPRESENTATION

$$\begin{aligned} \bar{\psi} = \psi^\dagger \gamma^0 &= (\psi^*)^T \gamma_0 = (\psi_1^*, \psi_2^*, \psi_3^*, \psi_4^*) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \\ &= (\psi_1^*, \psi_2^*, -\psi_3^*, -\psi_4^*) \end{aligned}$$

SOLUTIONS TO DIRAC EQUATION

CONSTRUCT WAVE FUNCTIONS \rightarrow CALCULATE PHYSICAL PROCESSES

FREE PARTICLE PLANE WAVE

$$\Psi(\vec{x}, t) = u(E, \vec{p}) e^{i(\vec{p} \cdot \vec{x} - Et)} \leftarrow \text{SPACE, TIME DEPENDENCE}$$

SATISFIES

$$(i\gamma^\mu \partial_\mu - m)\Psi = 0$$

4 COMPONENT SPINOR FUNCTION OF E, \vec{p}

DERIVATIVES ACT ON EXPONENTS

$$\partial_0 \Psi = -iE\Psi, \quad \partial_1 \Psi = ip_x \Psi \quad \dots \quad y \quad \dots \quad z$$

$$(\gamma^0 E - \gamma^1 p_x - \gamma^2 p_y - \gamma^3 p_z - m) u(E, \vec{p}) e^{i(\vec{p} \cdot \vec{x} - Et)} = 0$$

4 COMPONENT SPINOR $u(E, \vec{p})$ SATISFIES

no i \rightarrow $(\gamma^\mu p_\mu - m)u = 0$

PARTICLE AT REST

$$\bar{\phi} = 0 \rightarrow \psi = u(E, 0) e^{-iEt}$$

$$(\gamma^\mu p_\mu - m) u \rightarrow E \gamma^0 u = m u$$

$$E \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{pmatrix} = m \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{pmatrix}$$

γ^0 DIAGONAL — 4 ORTHOGONAL SOLUTIONS

$$u_1(E, 0) = N \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$u_2(E, 0) = N \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

+VE EIGENVALUES

$$E = +m$$

$$u_3(E, 0) = N \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$u_4(E, 0) = N \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

-VE EIGENVALUES

$$E = -m$$

$$\begin{array}{l}
 U_1(E, 0) \quad U_2(E, 0) \\
 U_3(E, 0) \quad U_4(E, 0)
 \end{array}
 \begin{array}{l}
 \text{ALSO} \\
 \text{EIGENSTATES} \\
 \text{OF}
 \end{array}
 \hat{S}_z = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \text{ SPIN}$$

$U_1(E, 0) \quad U_2(E, 0)$ SPIN UP AND DOWN +VE ENERGY

$U_3(E, 0) \quad U_4(E, 0)$ SPIN UP AND DOWN -VE ENERGY

PUTTING TIME DEPENDENCE IN

$$\psi_1 = N \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} e^{-imt}, \quad \psi_2 = N \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} e^{-imt} \quad m +ve$$

$$\psi_3 = N \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} e^{+imt}, \quad \psi_4 = N \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} e^{+imt} \quad m -ve$$

GENERAL FREE PARTICLE SOLUTIONS

DIRECTLY SOLVE DIRAC FOR GENERAL PLANE WAVE SOLN.

$$\Psi(\vec{x}, t) = U(E, \vec{p}) e^{i(\vec{p} \cdot \vec{x} - E \cdot t)}$$

FOUND THAT DE FOR SPINOR IS $(\gamma^\mu p_\mu - m)U = 0$
WRITE OUT IN COMPONENTS

$$(E\gamma^0 - p_x\gamma^1 - p_y\gamma^2 - p_z\gamma^3 - m)U = 0$$

IN DIRAC - PAULI REP:

$$\left[\begin{pmatrix} \mathbb{I} & 0 \\ 0 & -\mathbb{I} \end{pmatrix} E - \begin{pmatrix} 0 & \vec{\sigma} \cdot \vec{p} \\ -\vec{\sigma} \cdot \vec{p} & 0 \end{pmatrix} - m \begin{pmatrix} \mathbb{I} & 0 \\ 0 & \mathbb{I} \end{pmatrix} \right] U = 0 \quad (4.4)$$

↖ 2x2 MATRICES

$$\vec{\sigma} \cdot \vec{p} = \sigma_x p_x + \sigma_y p_y + \sigma_z p_z = \begin{pmatrix} p_z & p_x - i p_y \\ p_x + i p_y & -p_z \end{pmatrix}$$

u_A, u_B 2 COMPONENT COLUMN VECTORS $u = \begin{pmatrix} u_A \\ u_B \end{pmatrix}$
EXPRESS PREVIOUS MATRIX EQTN 4.4

$$\begin{pmatrix} (E-m)\mathbb{I} & -\vec{\sigma} \cdot \vec{p} \\ \vec{\sigma} \cdot \vec{p} & -(E+m)\mathbb{I} \end{pmatrix} \begin{pmatrix} u_A \\ u_B \end{pmatrix} = 0$$

THIS GIVES 2 COUPLED EQUATIONS!

$$u_A = \frac{\vec{\sigma} \cdot \vec{p}}{E-m} \cdot u_B ; \quad u_B = \frac{\vec{\sigma} \cdot \vec{p}}{E+m} \cdot u_A$$

CAN USE THESE EQUATIONS TO CONSTRUCT FOUR ORTHOGONAL SOLUTIONS u_1, u_2, u_3, u_4 BY SUCCESSIVELY CHOOSING

$$u_A = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad u_A = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad u_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad u_B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned}
 U_A = \begin{pmatrix} 1 \\ 0 \end{pmatrix} &\rightarrow U_B = \frac{\vec{\sigma} \cdot \vec{P}}{E+m} U_A = \frac{1}{E+m} \begin{pmatrix} p_z & p_x - ip_y \\ p_x + ip_y & -p_z \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\
 &= \frac{1}{E+m} \begin{pmatrix} p_z \\ p_x + ip_y \end{pmatrix}
 \end{aligned}$$

$$U_1 = \begin{pmatrix} U_A \\ U_B \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ \frac{p_z}{E+m} \\ \frac{p_x + ip_y}{E+m} \end{pmatrix}$$

$$u_A = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rightarrow u_B = \frac{\vec{\sigma} \cdot \vec{P}}{E+m} u_A = \frac{1}{E+m} \begin{pmatrix} p_z & p_x - ip_y \\ p_x + ip_y & -p_z \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$= \frac{1}{E+m} \begin{pmatrix} p_x - ip_y \\ -p_z \end{pmatrix}$$

$$u_2 = \begin{pmatrix} u_A \\ u_B \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ \frac{p_x - ip_y}{E+m} \\ \frac{-p_z}{E+m} \end{pmatrix}$$

THEN CHOSE $u_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $u_B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

FOUR ORTHOGONAL SOLUTIONS

$$\psi_i = u_i(E, \vec{p}) e^{i(\vec{p} \cdot \vec{x} - Et)}$$

$$u_1 = N \begin{pmatrix} 1 \\ 0 \\ \frac{p_z}{E+m} \\ \frac{p_x + i p_y}{E+m} \end{pmatrix}$$

$$u_2 = N \begin{pmatrix} 0 \\ 1 \\ \frac{p_x - i p_y}{E+m} \\ -\frac{p_z}{E+m} \end{pmatrix}$$

$$u_3 = N \begin{pmatrix} \frac{p_z}{E-m} \\ \frac{p_x + i p_y}{E-m} \\ 0 \\ 0 \end{pmatrix}$$

$$u_4 = N \begin{pmatrix} \frac{p_x - i p_y}{E-m} \\ -\frac{p_z}{E-m} \\ 0 \\ 0 \end{pmatrix}$$

IF ANY ONE OF THE SPINORS u_1 u_2 u_3 u_4
 ARE SUBSTITUTED INTO DE GET $E^2 = p^2 + m^2$

$\vec{p} = 0$ GET

$$\underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}}_{E +ve} \quad \underbrace{\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}}_{E -ve}$$

← DO IT!

IDENTIFY u_1 u_2 $E = + \left| \sqrt{p^2 + m^2} \right|$ $E +ve$

u_3 u_4 $E = - \left| \sqrt{p^2 + m^2} \right|$ $E -ve$

CAN ALL FOUR HAVE $E > 0$???

→ EXPONENT OF $\psi_i = u_i e^{i(\vec{p} \cdot \vec{x} - Et)}$ SAME FOR ALL

FOUR NO
 LONGER INDEP

→ $u_1 = \frac{p_z}{E+m} u_3 + \frac{p_x + ip_y}{E+m} u_4$

\hat{H}_D 4×4 , $\text{Tr} = 0 \Rightarrow$ EQUAL NUMBERS OF +ve
 AND -ve ENERGY SOLUTIONS

ANTI PARTICLES

QUANTUM MECHANICS → COMPLETE SET OF BASIS STATES

DIRAC REALIZED WHAT THE PROBLEM WAS WITH RELATIVISTIC QUANTUM MECHANICS

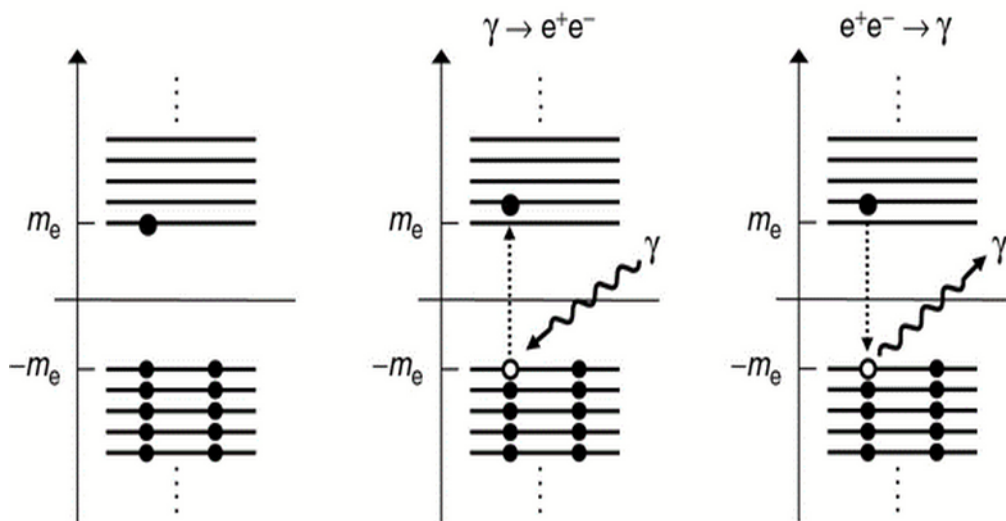
→ SINGLE PARTICLE THEORY

→ NEED THEORY FOR CREATION + ANNIHILATION OF PARTICLES

↳ QUANTUM FIELD THEORY

EXPERIMENTALLY ANTI PARTICLES HAVE SAME MASS, SPIN, BUT OPPOSITE ELECTRIC CHARGE, AND OPPOSITE OF SOME OTHER INTERNAL QUANTUM NUMBERS

DIRAC "SEA"



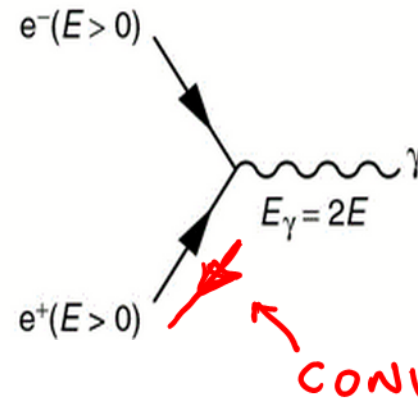
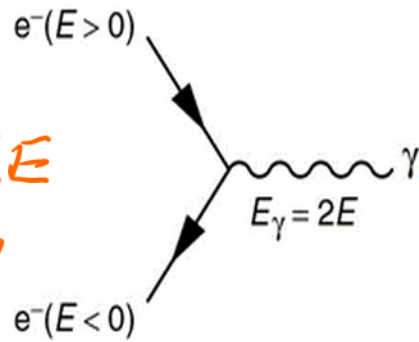
WHAT DO THE NEGATIVE ENERGY SOLUTIONS
CORRESPOND TO?

ANTIPARTICLE \rightarrow "HOLE" IN NEGATIVE SEA

ONLY OF HISTORICAL INTEREST

FEYNMAN - STÜCKELBERG

ELECTRON
EMITS $E_\gamma = 2E$
-VE ENERGY
MOVES BACK
IN TIME



ELECTRON AND
POSITRON
ANNIHILATE
TO $E_\gamma = 2E$

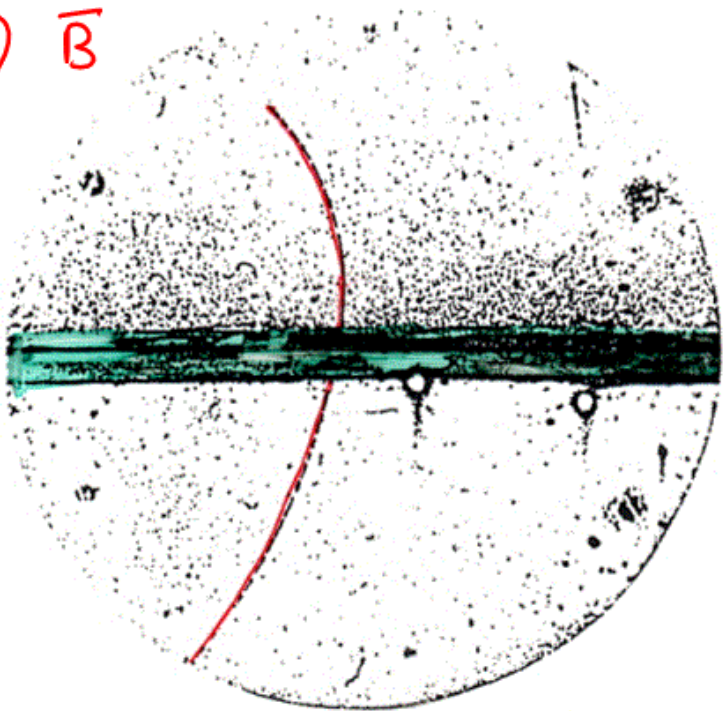
$E < 0$ SOLUTIONS ARE NEGATIVE PARTICLES MOVING
BACKWARDS IN TIME

COMPLETELY EQUIVALENT TO POSITIVE CHARGE
MOVING FORWARDS IN TIME

$$\exp(-iEt) \equiv \exp(-i(-E)(-t))$$

"ONLY THE MATHEMATICS COUNTS"

(X) \bar{B}

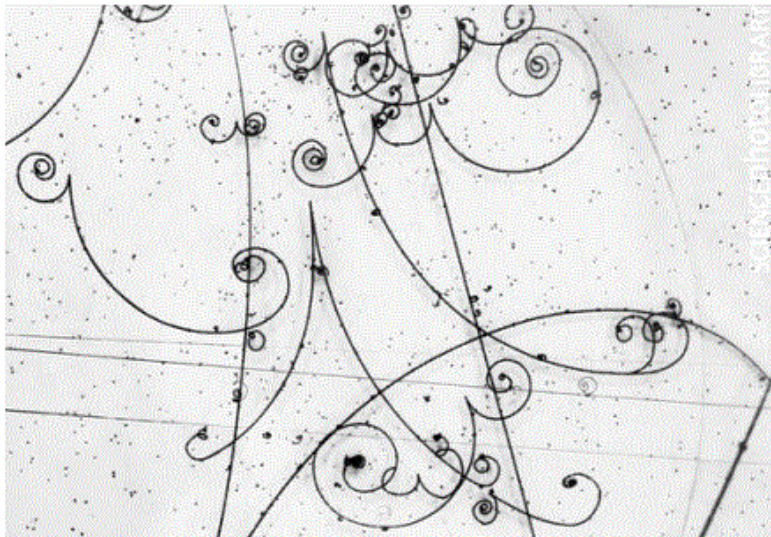


Pb
PLATE

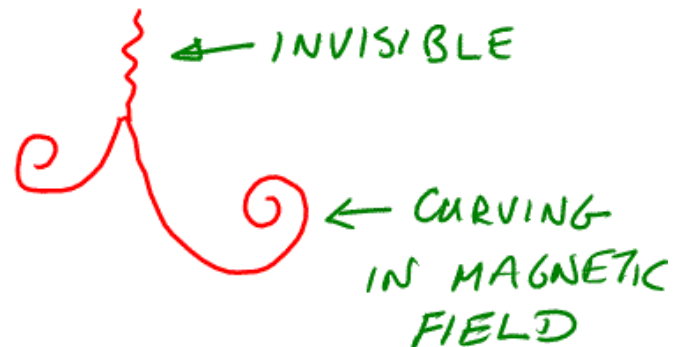
• DISCOVERY OF POSITRON
BY CARL ANDERSON 1933

- PARTICLE SLOWS DOWN IN
Pb PLATE \therefore COMING FROM
BELOW
- FROM SIGN OF MAGNETIC
FIELD MUST B +VE
- 10X RANGE OF PROTON
(ONLY +VE PARTICLE KNOWN)

A 63 million volt positron ($H_p = 2.1 \times 10^6$ gauss-cm) passing through a 6 mm lead plate and emerging as a 23 million volt positron ($H_p = 7.5 \times 10^5$ gauss-cm). The length of this latter path is at least ten times greater than the possible length of a proton path of this curvature.



$\gamma \rightarrow e^+e^-$ IN A LARGE
MODERN BUBBLE
CHAMBER



ANTI PARTICLE SPINORS

COULD CALCULATE USING NEGATIVE ENERGY SPINORS \rightarrow BUT THEN WOULD HAVE TO KEEP IN MIND ENERGY IN SPINOR IS NEGATIVE OF PHYSICAL ENERGY

ALSO SINCE u_3, u_4 BACKWARDS IN TIME, SPINOR MOMENTUM NEGATIVE OF PHYSICAL MOMENTUM. USE SPINORS WITH PHYSICAL ENERGY AND MOMENTUM NEGATIVE ENERGY SPINORS CAN BE REWRITTEN BY JUST REVERSING SIGNS ON E & \vec{p}

$$v_1(E, \vec{p}) e^{-i(\vec{p} \cdot \vec{x} - Et)} \rightarrow u_4(-E, -\vec{p}) e^{+i(-\vec{p} \cdot \vec{x} - (-E)t)}$$

$$v_2(E, \vec{p}) e^{-i(\vec{p} \cdot \vec{x} - Et)} \rightarrow u_3(-E, -\vec{p}) e^{+i(-\vec{p} \cdot \vec{x} - (-E)t)}$$

IDENTIFY ANTI PARTICLE SPINORS BY LOOKING FOR DIRAC EQUATION SOLUTIONS

$$\psi(\vec{x}, t) = v(E, \vec{p}) e^{-i(\vec{p} \cdot \vec{x} - Et)}$$

FOR PHYSICAL $E > 0$, STILL "-VE ENERGY SOLN"

$$i \frac{\partial}{\partial t} \psi = -E \psi$$

DIRAC $(i \gamma^\mu \partial_\mu - m) \psi = 0$

$$(-\gamma^0 E + \gamma^1 p_x + \gamma^2 p_y + \gamma^3 p_z - m) v = 0$$

$$(\gamma^\mu p_\mu + m) v = 0$$

DIRAC EQUATION FOR ANTI PARTICLE SPINORS

v

AS BEFORE WRITE $\psi = \begin{pmatrix} \psi_A \\ \psi_B \end{pmatrix}$ AND GET:

$$\psi_A = \frac{\vec{\sigma} \cdot \vec{p}}{E+m} \psi_B \quad ; \quad \psi_B = \frac{\vec{\sigma} \cdot \vec{p}}{E-m} \psi_A$$

$$\psi_1 = N \begin{pmatrix} \frac{p_x - i p_y}{E+m} \\ -p_z \\ \frac{p_x + i p_y}{E+m} \\ 0 \\ 1 \end{pmatrix}$$

$$\psi_2 = N \begin{pmatrix} \frac{p_z}{E+m} \\ p_x + i p_y \\ \frac{p_x - i p_y}{E+m} \\ 0 \\ 1 \end{pmatrix}$$

$$E = + \sqrt{\vec{p}^2 + m^2}$$

$$E = - \sqrt{\vec{p}^2 + m^2} \quad \psi_3 = N \begin{pmatrix} 1 \\ 0 \\ \frac{p_z}{E+m} \\ \frac{p_x + i p_y}{E+m} \\ 0 \end{pmatrix}$$

$$\psi_4 = N \begin{pmatrix} 0 \\ 1 \\ \frac{p_x - i p_y}{E+m} \\ -p_z \\ \frac{p_x + i p_y}{E+m} \end{pmatrix}$$

WAVE FUNCTION NORMALIZATION

HAVE TO DETERMINE NORMALIZATION N

$$\rho = \psi^\dagger \psi = (\psi^*)^T \psi = U_1^\dagger U_1$$

$$U_1^\dagger U_1 = N^2 \left(1, 0, \frac{p_z}{E+m}, \frac{p_x - i p_y}{E+m} \right) \begin{pmatrix} 1 \\ 0 \\ \frac{p_z}{E+m} \\ \frac{p_x + i p_y}{E+m} \end{pmatrix}$$

$$= N^2 \left(1 + \frac{p_z^2}{(E+m)^2} + \frac{p_x^2 + p_y^2}{E+m^2} \right)$$

$$= N^2 \left(\frac{(E+m)^2 + p^2}{(E+m)^2} \right)$$

$$= N^2 \left(\frac{(E+m)^2 + E^2 - m^2}{(E+m)^2} \right) \rightarrow$$

$$U U^\dagger = 2E \text{ PARTICLES}$$

$$2E = \frac{N^2 2E}{E+m}$$

$$N = \sqrt{E+m}$$

HAVE 8 SOLUTIONS, ONLY 4 INDEPENDENT
 USE +VE PHYSICAL ENERGY u_1, u_2, v_1, v_2

$$u_1(p) = \sqrt{E+m} \begin{pmatrix} 1 \\ 0 \\ \frac{p_z}{E+m} \\ \frac{p_x + i p_y}{E+m} \end{pmatrix}$$

↑
4-VECTOR

$$u_2(p) = \sqrt{E+m} \begin{pmatrix} 0 \\ 1 \\ \frac{p_x - i p_y}{E+m} \\ -\frac{p_z}{E+m} \end{pmatrix}$$

$$v_1(p) = \sqrt{E+m} \begin{pmatrix} \frac{p_x - i p_y}{E+m} \\ -\frac{p_z}{E+m} \\ 0 \\ 1 \end{pmatrix}$$

$$v_2(p) = \sqrt{E+m} \begin{pmatrix} \frac{p_z}{E+m} \\ \frac{p_x + i p_y}{E+m} \\ 1 \\ 0 \end{pmatrix}$$

SUBTLE POINT FOR ANTIPARTICLES

$$\psi = \mathcal{U}(E, \vec{p}) e^{-i(\vec{p} \cdot \vec{x} - Et)}$$

SO

$$\hat{H}\psi = i \frac{\partial \psi}{\partial t} = -E \quad , \quad \hat{\vec{p}}\psi = -i \vec{\nabla} \psi = -\vec{p} \psi$$

MINUS \rightarrow \mathcal{U} ARE STILL -VE ENERGY SOLUTIONS

REWRITTEN IN TERMS OF PHYSICAL E, \vec{p}

RELEVANT OPERATORS ARE:

$$\hat{H}^{(v)} = -i \partial / \partial t \quad , \quad \hat{\vec{p}}^{(v)} = +i \vec{\nabla}$$

$$(E, \vec{p}) \rightarrow (-E, -\vec{p}) \quad \vec{L} = \vec{r} \times \vec{p} \rightarrow -\vec{L}$$

$$\hat{\vec{S}}^{(v)} = -\vec{S}$$

