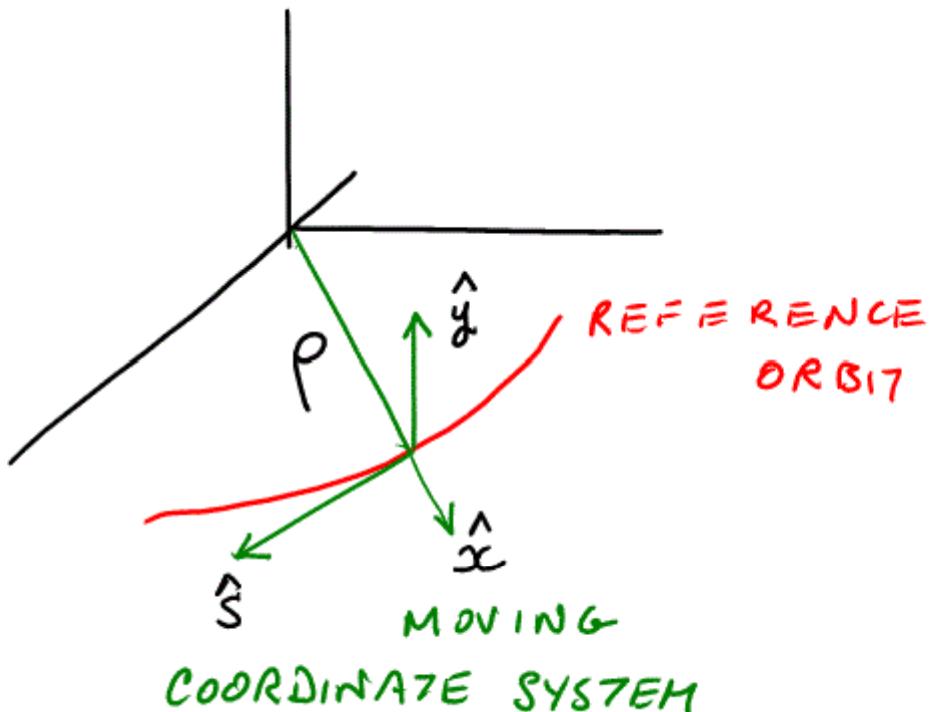


ORBITAL STABILITY

- IN DISCUSSION OF BETATRON OSCILLATIONS IN A WEAKLY FOCUSED MACHINE DERIVED CONDITIONS FOR STABILITY AROUND EQUILIBRIUM ORBIT
- FOR STRONG FOCUSING THE FIELD INDEX CAN BE $\gg 1$. IN FACT, WE CAN IMAGINE THAT IT WILL VARY AROUND THE RING
- WANT TO STUDY
 - SPATIAL STABILITY OF BEAM ENVELOPE \rightarrow BETATRON OSCILLATIONS
 - PHASE STABILITY w.r.t. THE PHASE OF ACCELERATING VOLTAGE \rightarrow SYNCHROTRON OSCILLATIONS

WORK IN MOVING COORDINATE SYSTEM

- EQUILIBRIUM ORBIT IN A PARTICULAR MACHINE IS DEFINED BY CHOSEN MAGNET CONFIGURATION
- OUR MAIN INTEREST IS IN UNDERSTANDING HOW PARTICLES MOVE RELATIVE TO EQUILIBRIUM ORBIT
- MOTION EASIER TO TREAT IN COORDINATE SYSTEM THAT MOVES ALONG EQUILIBRIUM ORBIT.



POSITION OF PARTICLE



$$\vec{r} = r \hat{x} + y \hat{y}; r = p + \alpha$$

EQUATION OF MOTION

$$\frac{d\vec{P}}{dt} = e \vec{v} \times \vec{B}$$

MAGNETIC FIELD \rightarrow RADIAL & VERTICAL COMPONENTS
 \rightarrow NO COMPONENT IN \hat{S} -DIRECTION

$$\bar{v} \times \bar{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ v_x & v_y & v_z \\ B_x & B_y & 0 \end{vmatrix} = -v_z B_y \hat{x} + v_z B_x \hat{y} + (v_x B_y - v_y B_x) \hat{z}$$

ASSUME NO ENERGY CHANGE \rightarrow NO ACCELERATION \wedge
 \rightarrow NO SYNCHROTRON RADIATION

$$e \vec{v} \times \vec{B} = \frac{d\vec{p}}{dt} = \frac{d}{dt} (\gamma m \vec{R}) = \gamma m \ddot{\vec{R}}$$

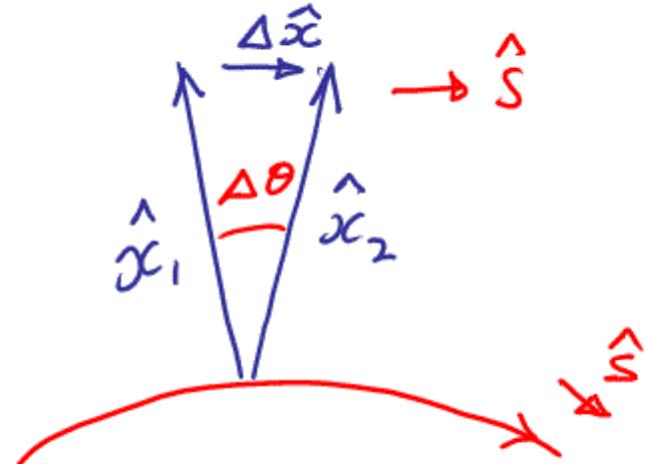
$$\frac{1}{R} = \frac{e \bar{v} \times \vec{B}}{\gamma m}$$

EVALUATE THIS IN LOCAL MOVING COORD SYSTEM

$$\vec{R} = r\hat{x} + y\hat{y} \rightarrow \vec{R} = r'\hat{x} + r\dot{\hat{x}} + \vec{y}\hat{y}$$

VARIABLE IN TIME  *CONSTANT* 

VARIATION IN TIME OF UNIT VECTORS

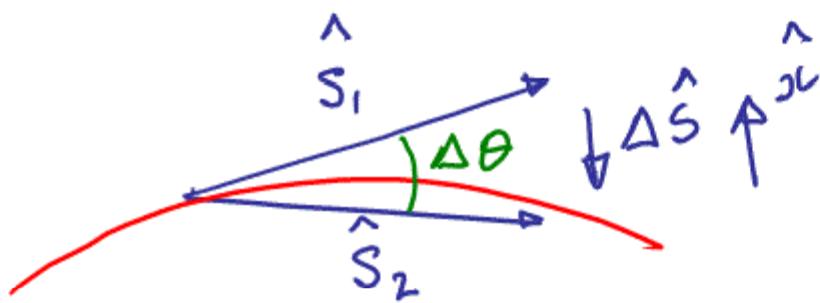


$$\Delta \hat{x} = \underbrace{|\hat{x}|}_{\text{MAG}} \underbrace{\Delta \theta}_{\text{DIRECTION}} \cdot \hat{s}$$

≡ 1

ASSUME \hat{s} CONSTANT

$$\dot{\hat{x}} = \dot{\theta} \cdot \hat{s}$$



$$\Delta \hat{s} = |\hat{s}| \Delta \theta (-\hat{x})$$

$$\dot{\hat{s}} = -\dot{\theta} \hat{x}$$

$$\dot{\theta} = \frac{v_s}{r}$$

HAD $\dot{\vec{R}} = \dot{r}\hat{x} + r\dot{\theta}\hat{s} + \dot{\phi}\hat{y}$

$$\dot{\vec{R}} = \dot{r}\hat{x} + r\dot{\theta}\hat{s} + \dot{\phi}\hat{y}$$

$\underline{\text{VARIES IN TIME}}$

$$\ddot{\vec{R}} = \ddot{r}\hat{x} + \dot{r}\hat{x} + r\frac{d}{dt}(\dot{\theta}\hat{s}) + \dot{\theta}\hat{s}\dot{r} + \ddot{\phi}\hat{y}$$

$$= \ddot{r}\hat{x} + \dot{r}\hat{x} + r\dot{\theta}\hat{s} + r\ddot{\theta}\hat{s} + \dot{\theta}\hat{s}\dot{r} + \ddot{\phi}\hat{y}$$

\downarrow
 $\dot{\theta}\hat{s}$

$$= \ddot{r}\hat{x} + (2\dot{r}\theta + r\ddot{\theta})\hat{s} + r\dot{\theta}\hat{s} + \ddot{\phi}\hat{y}$$

$$\ddot{\vec{R}} = \ddot{r}\hat{x} + (2\dot{r}\theta + r\ddot{\theta})\hat{s} - r\dot{\theta}^2\hat{x} + \ddot{\phi}\hat{z}$$

$$\ddot{\vec{R}} = \underbrace{(\ddot{r} - r\dot{\theta}^2)}_{\text{RADIAL MOTION}}\hat{x} + \underbrace{(2\dot{r}\theta + r\ddot{\theta})}_{\text{ALONG ORBIT}}\hat{s} + \underbrace{\ddot{\phi}\hat{z}}_{\text{VERTICAL}}$$

X OR RADIAL MOTION FROM

$$\ddot{R} = (\ddot{r} - r\dot{\theta}^2) \hat{x} + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \hat{s} + \ddot{\theta} \hat{y}$$

$$F = \gamma m \ddot{x}$$

$$e(\vec{v} \times \vec{B})_x = -e v_s B_y \hat{x} = \frac{d\vec{p}}{dt} = \gamma m (\ddot{r} - r\dot{\theta}^2) \hat{x}$$

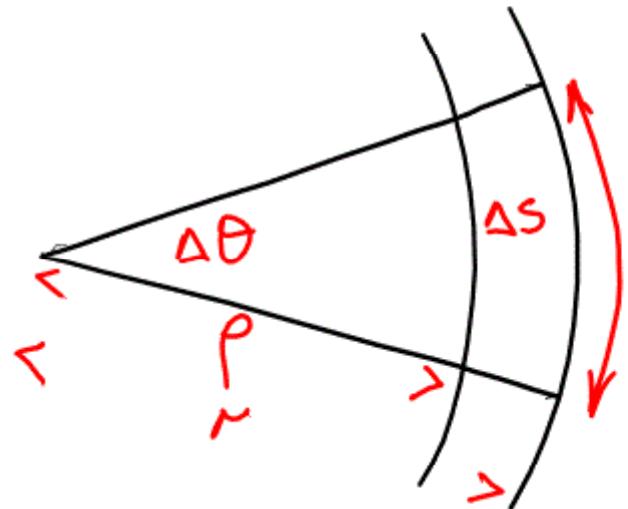
EQUATION OF MOTION $(\ddot{r} - r\dot{\theta}^2) = -e v_s B_y / \gamma m$

FOR $v_{sc} \ll v_s$; $v_y \ll v_s$ $\Rightarrow \gamma m v_s$

$$\ddot{r} - r\dot{\theta}^2 = -\frac{e v_s^2 B_y}{\gamma}$$

IN AN ACCELERATOR MORE INTERESTED
IN HOW MOTION VARIES ALONG PERIODIC ORBIT.

CHANGE VARIABLE $t \rightarrow s$



$$\Delta s = \rho \Delta \theta$$

$$v_s \Delta t = r \Delta \theta$$

$$\Delta t = \frac{r}{v_s} \cdot \Delta \theta$$

$$\Delta t = \frac{r}{v_s} \cdot \frac{\Delta s}{\rho}$$

$$\frac{1}{\Delta t^2} = v_s^2 \left(\frac{\rho}{r} \right)^2 \frac{1}{\Delta s^2}$$

$$\frac{d}{dt} = \frac{ds}{dt} \cdot \frac{d}{ds}$$

HAD

$$\frac{d^2 r}{dt^2} - r \left(\frac{d\theta}{dt} \right)^2 = - \frac{e v_s^2}{\rho} B_y$$

$\hookrightarrow r = \rho + x \rightarrow \rho \text{ is constant}$

$$\frac{d\theta}{dt} = \frac{v_s}{r}$$

$$\frac{d^2 \theta}{dt^2} - r \left(\frac{v_s}{r} \right)^2 = - e \frac{v_s^2}{\rho} \cdot B_y$$

$$\frac{1}{\Delta t^2} = v_s^2 \left(\frac{\rho}{r} \right)^2 \frac{1}{\Delta s^2} \rightarrow v_s^2 \frac{\rho^2}{r^2} \cdot \frac{d^2 x}{ds^2} - r \frac{v_s^2}{r^2} = - \frac{e v_s^2}{\rho} B_y$$

$$\frac{e}{\rho} = \frac{1}{B\rho} \rightarrow \frac{d^2 x}{ds^2} - \frac{r}{\rho^2} = - \frac{r^2}{\rho^2} \cdot \frac{B_y}{B\rho}$$

$$r = \rho + x \rightarrow \frac{d^2 x}{ds^2} - \left(\frac{\rho + x}{\rho^2} \right) = - \left(1 + \frac{x}{\rho} \right)^2 \frac{B_y}{B}$$

EQUATION OF MOTION IN x -DIRECTION

y -DIRECTION, HAD:

$$\ddot{\vec{R}} = (\ddot{r} - r\dot{\theta}^2)\hat{r} + (2\dot{r}\dot{\theta} + r\ddot{\theta})\hat{s} + \ddot{y}\hat{y}$$

$$F = \gamma m \ddot{y}$$

$$e(\vec{v} \times \vec{B})_y = +e v_s B_x \hat{y} = \gamma_m \ddot{y} \hat{y}$$

$$v_x, v_y \ll v_s \quad p \rightarrow \gamma_m v_s$$

$$\frac{d^2 y}{dt^2} = -e \frac{v_s^2}{p} \cdot v_s$$

CHANGE $dt^2 \rightarrow ds^2$

$$\frac{d^2 y}{ds^2} = + \left(1 + \frac{x}{p^2} \right) \frac{B_x}{B p}$$

EQUATION OF MOTION IN y -DIRECTION

IN ENGINEERING TERMS, THE MAGNETIC FIELDS CAN BE QUITE COMPLEX - NONLINEAR
BUT ASSUME LINEAR FOR SIMPLICITY

$$B_x = B_{x0}(0,0) + \frac{\partial B_x}{\partial y} \cdot y + \frac{\partial B_x}{\partial z} \cdot z \quad \left. \right\}$$

$$B_y = B_{y0}(0,0) + \frac{\partial B_y}{\partial z} \cdot z + \frac{\partial B_y}{\partial y} \cdot y \quad \left. \right\}$$

$$B_{x0}(0,0) = 0 \quad ; \quad B_{y0}(0,0) \rightarrow B$$

DON'T WANT x & y MOTION COUPLED

$$\therefore \text{ASSUME } \frac{\partial B_x}{\partial z} = \frac{\partial B_y}{\partial y} = 0$$

$$B_x = \frac{\partial B_x}{\partial y} \cdot y$$

$$B_y = B + \frac{\partial B_y}{\partial x} \cdot x$$

$$\nabla \times \vec{B} = 0 \rightarrow \left(\frac{\partial B_x}{\partial y} - \frac{\partial B_y}{\partial x} \right) = 0$$

$$B_x = \frac{\partial B_y}{\partial x} \cdot y$$

$$B_y = B + \frac{\partial B_y}{\partial x} \cdot x$$

MOTION IN x -DIRECTION

$$\frac{d^2x}{ds^2} + \frac{\rho+x}{\rho^2} + \left(1 + \frac{x}{\rho}\right)^2 \cdot \frac{1}{B\rho} \frac{\partial B_y(s)}{\partial x} \cdot x = 0$$

FOR small x $\left(1 + \frac{x}{\rho}\right)^2 \sim \left(1 + \frac{x}{\rho}\right)$

$$\frac{\partial B_y(s)}{\partial x} = B + x \frac{\partial B_y}{\partial x}$$

$$\left(B + x \frac{\partial B_y}{\partial x}\right) \left(1 + \frac{x}{\rho}\right) \frac{1}{B\rho} = \left(B + \frac{xB}{\rho} + \cancel{x^2 \frac{\partial B_y}{\partial x}} + x \frac{\partial B_y}{\partial x}\right) \frac{1}{B\rho}$$

$$\frac{d^2x}{ds^2} - \frac{1}{\rho} - \frac{x}{\rho^2} + \frac{1}{\rho} + \frac{2x}{\rho^2} + \frac{x}{B\rho} \frac{\partial B_y}{\partial x}$$

FOR SMALL OSCILLATIONS, $x \neq y$ EQUATIONS OF MOTION

$$\xrightarrow{x} \frac{d^2x}{ds^2} + \left[\frac{1}{\rho^2} + \frac{1}{B\rho} \cdot \frac{\partial B_y(s)}{\partial x} \right] \cdot x = 0 \quad (1)$$

$$\uparrow y \quad \frac{d^2y}{ds^2} - \frac{1}{B\rho} \cdot \frac{\partial B_y}{\partial x} \cdot y = 0 \quad (2)$$

IN (1) GO BACK TO FORM

$$\frac{d^2x}{ds^2} - \frac{\rho + x}{\rho^2} = - \frac{B_y}{B\rho} \left(1 + \frac{x}{\rho} \right)^2$$

ON EQUILIBRIUM ORBIT $\frac{d^2x}{ds^2} = 0 ; x = 0$

$\frac{1}{\rho} = \frac{B_y}{B\rho} \rightarrow \frac{1}{\rho} = \frac{e}{\rho} \cdot B_y \rightarrow$ CIRCULAR MOTION IN DIPOLE FIELD

EQUATIONS OF MOTION

$$\ddot{x} + \left[\frac{1}{\rho^2} + \frac{1}{B\rho} \frac{\partial B_y(s)}{\partial x} \right] \cdot x = 0 \quad (1)$$

OSCILLATIONS → $\frac{1}{\rho^2} \ll \frac{1}{B\rho}$

$$\ddot{y} - \frac{1}{B\rho} \cdot \frac{\partial B_y}{\partial x} \cdot y = 0 \quad (2)$$

BOTH ARE OF FORM

$$\ddot{x} + K(s)x = 0$$

HILL'S EQUATION
SIMPLE HARMONIC MOTION
WITH VARIABLE SPRING CONSTANT

TRANSVERSE OSCILLATIONS
VARY IN AMPLITUDE &
FREQUENCY ALONG ORBIT

PIECE WISE SOLUTION FOR REAL ACCELERATOR

$$x'' + k(s)x = 0$$

$k(s)$ CONSTANT IN EACH ELEMENT OF LATTICE \rightarrow DIPOLE, 4-POLE, DRIFT etc

- CAN USE SHM SOLUTION IN EACH ELEMENT & MATCH BOUNDARIES

$k=0$ DRIFT OR CONSTANT B_g

$k>0$ SIMPLE HARMONIC OSCILLATOR

$k<0$ HYPERBOLIC

$$K=0 \quad \begin{pmatrix} x \\ x' \end{pmatrix}_{\text{out}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_{\text{in}}$$

$$K>0 \quad \begin{pmatrix} x \\ x' \end{pmatrix}_{\text{out}} = \begin{pmatrix} \cos(\sqrt{K}\ell) & \frac{1}{\sqrt{K}} \sin(\sqrt{K}\ell) \\ -\sqrt{K} \sin(\sqrt{K}\ell) & \cos(\sqrt{K}\ell) \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_{\text{in}}$$

$K<0$

$$\begin{pmatrix} x \\ x' \end{pmatrix}_{\text{out}} = \begin{pmatrix} \cosh(\sqrt{|K|}\ell) & \frac{1}{\sqrt{|K|}} \sinh(\sqrt{|K|}\ell) \\ \sqrt{|K|} \sinh(\sqrt{|K|}\ell) & \cosh(\sqrt{|K|}\ell) \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_{\text{in}}$$

$\ell \rightarrow 0 \rightarrow \text{THIN LENS}$

ANALYTICAL SOLUTION OF HILL'S EQUATION.

WANT SOME FORMALISM WHICH DOES NOT JUST DESCRIBE ONE PARTICLE

• WANT TO DESCRIBE BEAM ENVELOPE \rightarrow ^{PHASE} AMPLITUDE

$$\ddot{x} + k(s)x = 0$$

FOR A PERIODIC STRUCTURE $k(s) = k(s+c)$

SOLUTION $x = A \omega(s) \cos(\phi(s) + \delta)$

$A, \delta \rightarrow$ INITIAL CONDITIONS
 K CONSTANT \rightarrow SHM $x = A \cos(\phi(s) + \delta)$

• A CONSTANT

• $\phi(s) = s\sqrt{k}$ INCREASES LINEARLY

HERE A VARIES WITH s , $\phi(s)$ DOES NOT INCREASE LINEARLY WITH s

TRY SOLUTION $x(s) = A\omega(s) \cos(\phi(s) + \delta)$

IN $\ddot{x} + K(s) \cdot x = 0$

$$\ddot{x} + Kx = A(2\dot{\omega}\phi' + \omega\phi'') \sin(\phi + \delta) +$$

$$A(\omega'' - \omega\phi'^2 + K\omega) \cos(\phi + \delta) = 0$$

IF δ ARBITRARY, COEFFICIENTS OF $\sin, \cos = 0$

$$\omega(2\dot{\omega}\phi' + \omega\phi'') = 0 \rightarrow (\omega^2\phi')' = 0$$

$$\phi' = k/\omega^2 \quad k \text{ CONSTANT OF INTEGRATION}$$

ABSORB INTO A , $k \rightarrow 1$

$$\phi' = \frac{1}{\omega^2}$$

COEFFICIENT OF COSINE TERM

$$\omega'' - \omega \phi'^2 + K(s) \omega \rightarrow \omega'' - \omega \cdot \frac{1}{\omega^4} + K(s) \omega = 0$$

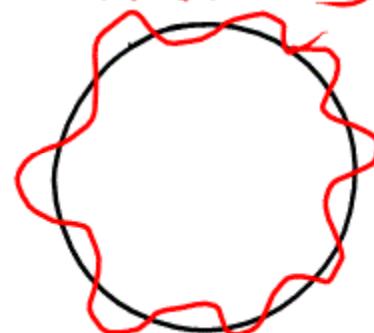
$$\omega^3 (\omega'' + K(s) \omega) = 1$$

NOW HAVE AN EQUATION FOR $\omega(s)$ AS
A FUNCTION OF POSITION AROUND
ACCELERATOR RING

$$x(s) = A \omega(s) \cos(\phi(s) + \delta)$$

$$\omega'' + K(s) \omega = \frac{1}{\omega^3} ; \quad \omega^2 \phi' = 1$$

AMPLITUDE OF TRANSVERSE OSCILLATIONS
AS A FUNCTION OF POSITION AROUND
ACCELERATOR RING



$$\omega'' + K(s) \omega = \frac{1}{\omega^3} ; \quad \omega^2 \phi' = 1$$

DEFINE COURANT - SNYDER PARAMETERS

$\beta(s) = \omega^2(s)$ AMPLITUDE FUNCTION

$$\alpha(s) = -\frac{1}{2} \beta'(s)$$

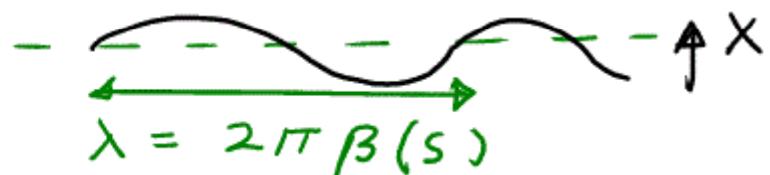
$$\gamma(s) = 1 + \alpha^2(s) / \beta(s)$$

$$so \quad \phi'(s) = \frac{1}{\beta(s)} \rightarrow \Delta\phi(s) = \int_0^s \frac{ds}{\beta(s)}$$

$$x = A \omega(s) \cos(\phi(s) + \delta) \quad \omega^2 \rightarrow \text{OSC FREQUENCY}$$

$2\pi\beta \rightarrow \text{OSCILLATION WAVE LENGTH}$

PHASE ADVANCE ALONG PATH S.



$$\text{HAD} \quad \omega'' - K(s)\omega - \frac{1}{\omega^3} = 0$$

$$\omega = \sqrt{\beta} \rightarrow \omega' = \frac{1}{2\sqrt{\beta}} \beta'$$

$$\omega'' = -\frac{1}{4} \beta^{-3/2} (\beta')^2 + \frac{1}{2} \beta^{-\frac{1}{2}} \beta''$$

$$\rightarrow \frac{1}{2} \beta^{-\frac{1}{2}} \beta'' - \frac{1}{4} (\beta')^2 + K \beta^2 - 1 = 0$$

$$(2\beta\beta'' - \beta'^2 + 4K\beta^2) = 4$$

$$K\beta = \gamma + \alpha'$$

FOR A PERIODIC ACCELERATOR
PARTICLE ORBITS ARE SOLUTIONS OF

$$\begin{aligned} \ddot{x} + k(s)x &= 0 \\ \ddot{y} + k(s)y &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \textcircled{1}$$

AND $2\beta\beta'' - \beta'^2 + 4\beta^2 k(s) = 0 \quad \textcircled{2}$

- ① DESCRIBES INDIVIDUAL PARTICLE
- ② DESCRIBES BEAM ENVELOPE

CALL x or y

$$y'' + k(s)y = 0 \quad \text{SOLN} \quad y(s) = A\sqrt{\beta(s)} \cos(\phi(s) + \delta) \quad \textcircled{1}$$

Differentiate solution.

$$y'(s) = A \frac{d}{ds} \sqrt{\beta} \cos(\phi + \delta) + A \sqrt{\beta} \frac{d}{ds} \left\{ \cos(\phi + \delta) \right\}$$

$$\alpha(s) = -\frac{1}{2} \frac{d\beta}{ds}, \quad \frac{d\sqrt{\beta}}{ds} = -\frac{1}{\sqrt{\beta}} \cdot \alpha$$

Drop δ
FOR NOW

$$y' = -\frac{A\alpha}{\sqrt{\beta}} \cos \phi - A\sqrt{\beta} \frac{d\phi}{ds} \sin \phi \underbrace{- \frac{1}{\beta}}$$

$$y' = -\frac{A\alpha}{\sqrt{\beta}} \cos \phi - \frac{A}{\sqrt{\beta}} \sin \phi$$

$$\begin{aligned}\beta y' + \alpha y &= -A\sqrt{\beta} \alpha \cos \phi - A\sqrt{\beta} \sin \phi + A\sqrt{\beta} \alpha \cos \phi \\ &= -A\sqrt{\beta} \sin \phi \quad \textcircled{2}\end{aligned}$$

TAKE $\textcircled{1}^2 + \textcircled{2}^2$

$$(\beta y' + \alpha y)^2 + y^2 = A^2 \beta \sin^2 \phi + A^2 \beta \cos^2 \phi$$

$$\beta^2 y'^2 + \alpha^2 y^2 + y^2 + 2\alpha\beta y'y = A^2 \beta$$

$$\frac{1+\alpha^2}{\beta} y^2 + \beta y'^2 + 2\alpha y'y = A^2$$

γ

$$\beta y'^2 + 2\alpha y'y + \gamma y^2 = A^2$$

COURANT-SNYDER INVARIANT - BEAM EMMITTANCE

$$\textcircled{1} \quad \underbrace{\beta y'^2 + 2\alpha yy' + \gamma y^2 = A^2}_{\text{INITIAL CONDITIONS}} \quad \text{INVARIANT OF MOTION}$$

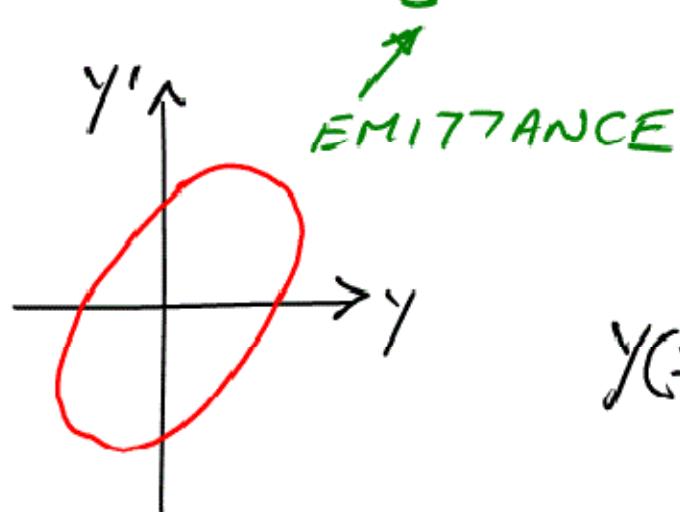
THIS IS AN ELLIPSE IN $Y Y'$ SPACE

$$\text{ELLIPSE} \quad a x^2 + 2 b x y + c y^2 = 1$$

$$\text{AREA} = \pi d / \sqrt{ac - b^2}$$

$$\text{IN } \textcircled{1} \quad \text{AREA} = \pi A^2 / \underbrace{\sqrt{\beta \gamma - \alpha^2}}_{=1} = \pi A^2$$

$$\text{DEFINE } \mathcal{E} = \pi A^2$$

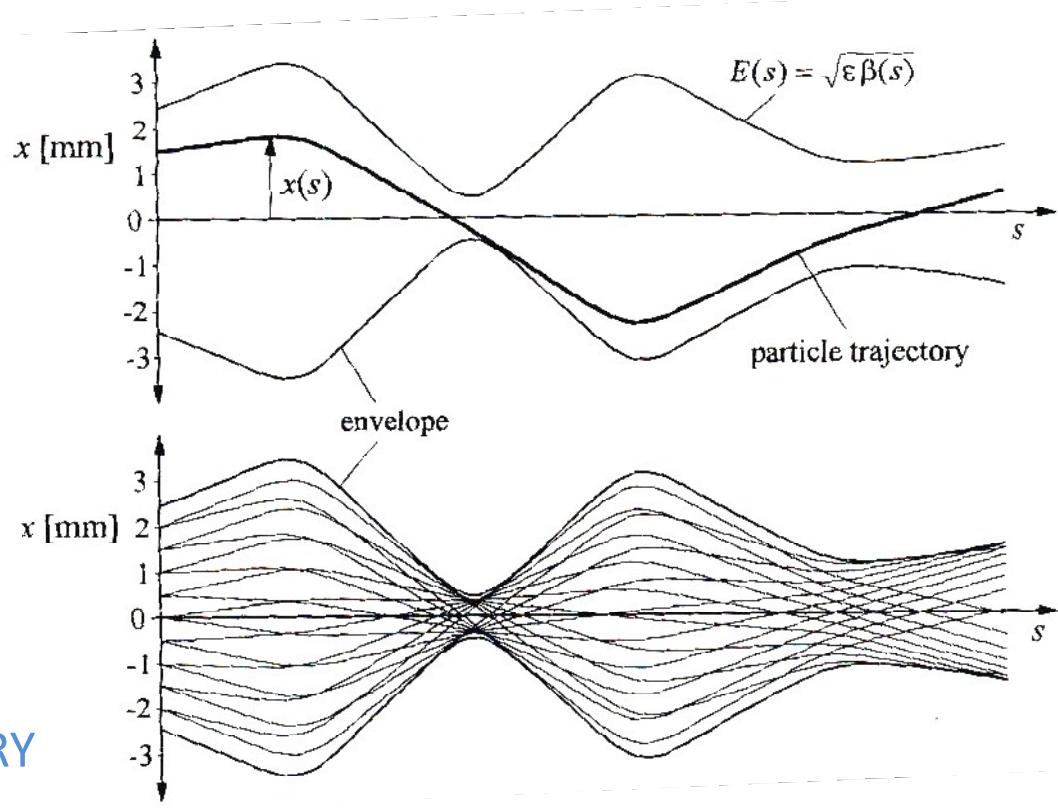


$$\beta y'^2 + 2\alpha yy' + \gamma y^2 = \frac{\mathcal{E}}{\pi}$$

$$y(s) = A \omega(s) \cos(\phi(s) + \delta)$$

$$y(s) = \sqrt{\frac{\mathcal{E} \beta(s)}{\pi}} \cos(\phi(s) + \delta)$$

TRAJECTORY



BEAM ENVELOPE

$$\frac{d^2 Y}{ds^2} + K(s)Y = 0$$

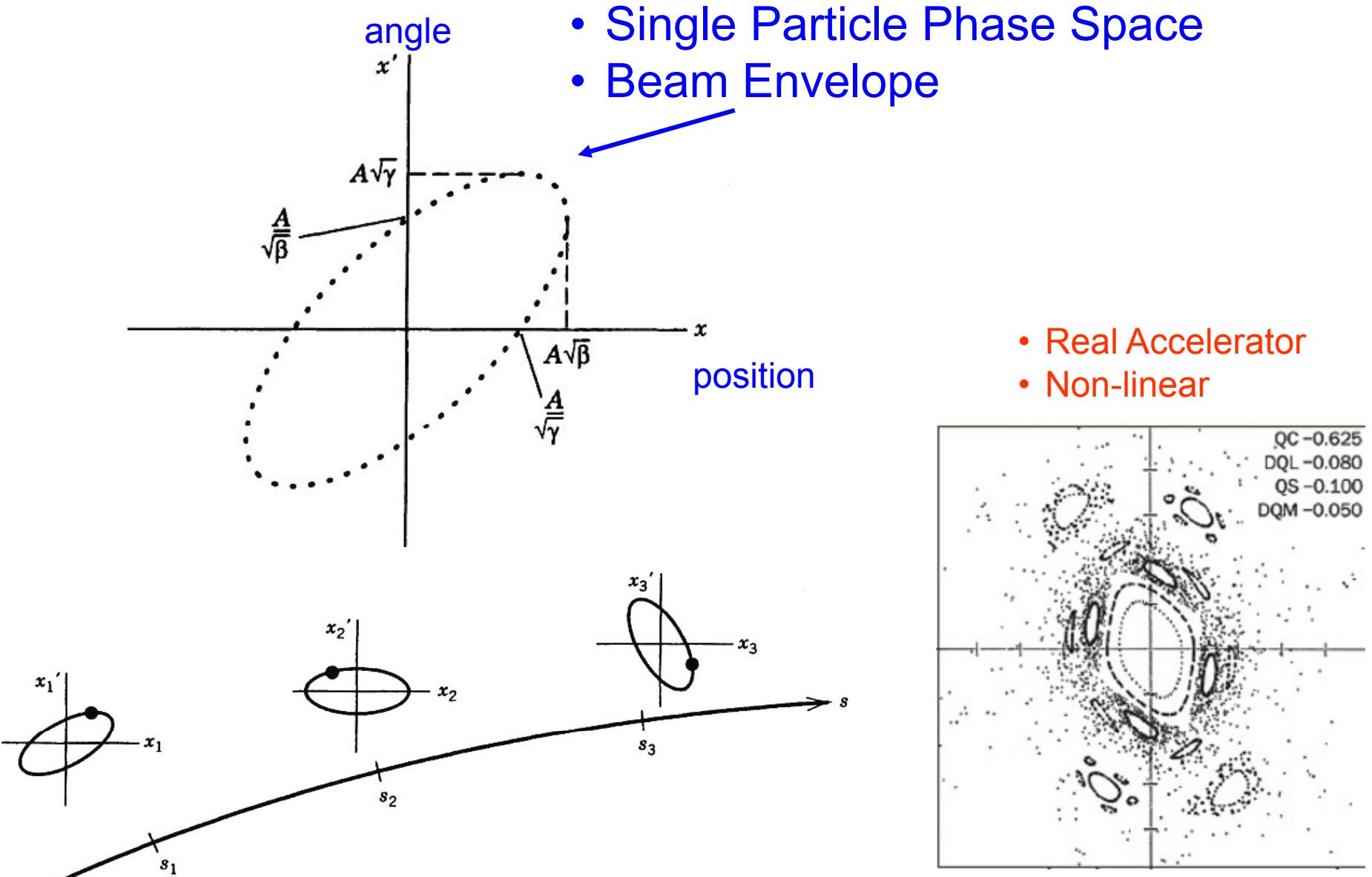
$$Y(s) = A\omega(s)\cos(\phi(s) + \delta)$$

$$Y(s) = \sqrt{\frac{\epsilon}{\pi}}\beta(s)\cos(\phi(s) + \delta)$$

$$\frac{d^2 \omega}{ds^2} + K(s)\omega = \frac{1}{\omega^3}$$

$$\beta(s) = \omega^2(s)$$

Amplitude of betatron oscillations



Shape of phase space changes along accelerator lattice
 Area constant \rightarrow Liouville

FROM ELLIPSE PLOT, AT ANY POINT IN ACCELERATOR MAXIMUM $x = A\sqrt{\beta}$
 AT SOME POINT IN THE LATTICE WILL HAVE APERTURE $2a$ WHICH DEFINES MAXIMUM ELLIPSE WHICH WILL FIT THRU MACHINE ADMITTANCE

$$2a(s) = 2A\sqrt{\beta} \rightarrow A^2 = a^2(s) / \beta$$

$$\beta y'^2 + 2\alpha y y' + \sigma y'^2 = \frac{\epsilon}{\pi} = A^2$$

$$\text{ADMITTANCE} = \frac{\pi a^3}{\beta_{\max}}$$

IN A REAL ACCELERATOR THERE ARE MANY PARTICLES

USUALLY ADMITTANCE / EMITTANCE DEFINED IN TERM OF PHASE SPACE BOUNDARY WHICH CONTAINS FRACTION F OF BEAM

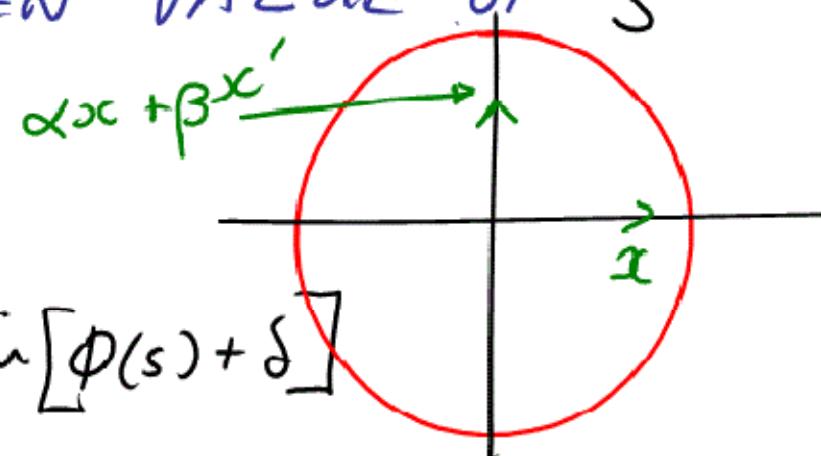
NUMBER DISTRIBUTION ASSUMED GAUSSIAN

$$n(x) dx = \frac{1}{\sqrt{2\pi} \cdot \sigma} \exp\left(\frac{-x^2}{2\sigma^2}\right) dx$$

ASSUME THIS DISTRIBUTION IS CONSTANT IN TIME AT A GIVEN VALUE OF s

$$x(s) = A\sqrt{\beta} \cos[\phi(s) + \delta]$$

$$\alpha(s)x(s) + \beta(s)\alpha'(s) = -A\sqrt{\beta} \sin[\phi(s) + \delta]$$



IN THIS TRANSFORMED PHASE SPACE
WHERE BOUNDARY IS A CIRCLE

$$\begin{aligned} & n(x, \alpha x + \beta x') dx d(\alpha x + \beta x') \\ &= \frac{1}{2\pi\sigma^2} e^{-[x^2 + (\alpha x + \beta x')^2]/2\sigma^2} \int d(\alpha x + \beta x') \end{aligned}$$

CHANGE TO POLAR COORDINATES

$$r^2 = x^2 + (\alpha x + \beta x')^2$$
$$n(r, \theta) r dr d\theta = \frac{1}{2\pi\sigma^2} e^{-r^2/2\sigma^2} r dr d\theta$$

IF FRACTION F OF BEAM IS WITHIN
RADIALS a

$$F = \int_0^{2\pi} \int_0^a n r dr d\theta = \int_0^a e^{-r^2/2\sigma^2} \frac{r dr}{\sigma^2}$$

$$F = \int_0^a e^{-r^2/2\sigma^2} \frac{r dr}{\sigma^2} \rightarrow a^2 = -2\sigma^2 \ln(1-F)$$

AND $\frac{\beta E}{\pi} = \beta \left(\frac{1+\alpha^2}{\beta} \right) x^2 + 2\alpha\beta xx' + \beta^2 x'^2$

$$= x^2 + (\alpha x + \beta x')^2$$

F contained in $a^2 = \frac{\beta E}{\pi} = -2\sigma^2 \ln(1-F)$

$E = -\frac{2\pi\sigma^2}{\beta} \ln(1-F)$	$\frac{E}{\sigma^2}/\beta$	$E \%$
	$\pi\sigma^2/\beta$	15
	$4\pi\sigma^2/\beta$	39
		87

IN DISCUSSING HILL'S EQUATION USE THE
SOLUTION $x(s) = A\omega(s) \cos(\phi(s) + \delta)$; $\dot{\phi}' = \frac{1}{\omega^2(s)}$

CAN ALSO WRITE AS:

$$x = \omega(s) (A_1 \cos \phi(s) + A_2 \sin \phi(s))$$

AND

$$x' = (A_1 \omega' + A_2 / \omega) \cos \phi + (A_2 \omega' - \frac{A_1}{\omega}) \sin \phi$$

INITIAL CONDITIONS $x_0, x'_0, s=s_0, \phi=0$

$$A_1 = \frac{x_0}{\omega} ; A_2 = x'_0 \omega - x_0 \omega'$$

GOING FROM $s_0 \rightarrow s_0 + c$ PERIOD OF SOLUTION $\omega(s_0 + c) = \omega(s_0)$

$$\begin{pmatrix} x \\ x' \end{pmatrix}_{s_0+c} = \begin{pmatrix} \cos \Delta\phi_c - \omega \omega' \sin \Delta\phi_c & \omega^2 \sin \Delta\phi_c \\ -\frac{1 + (\omega \omega')^2}{\omega^2} \sin \Delta\phi_c & \cos \Delta\phi_c + \omega \omega' \sin \Delta\phi_c \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_{s_0}$$

IN TERMS OF COURANT-SNYDER, LAST BECOMES

$$\begin{pmatrix} x \\ x' \end{pmatrix}_{S_0+c} = \begin{pmatrix} \cos \Delta\phi_c + \alpha \sin \Delta\phi_c & \beta \sin \Delta\phi_c \\ -\gamma \sin \Delta\phi_c & \cos \Delta\phi_c - \alpha \sin \Delta\phi_c \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_{S_0}$$

$$\phi(S_0 \rightarrow S_0 + c) = \Delta\phi_c = \int_{S_0}^{S_0+c} \frac{ds}{\omega^2(s)} = \int_{S_0}^{S_0+c} \frac{ds}{\beta(s)}$$

THIS TRANSFER MATRIX CAN BE WRITTEN

$$M = I \cos \Delta\phi_c + J \sin \Delta\phi_c$$

$$J = \begin{pmatrix} \alpha & \beta \\ -\gamma & -\alpha \end{pmatrix}; \quad J^2 = -I$$

OR

$$M = e^{J \Delta\phi_c}$$

SUPPOSE PRODUCT OF ALL TRANSFER MATRICES IN REPEAT PERIOD

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \cos \Delta\phi_c + \alpha \sin \Delta\phi_c & \beta \sin \Delta\phi_c \\ -\gamma \sin \Delta\phi_c & \cos \Delta\phi_c - \alpha \sin \Delta\phi_c \end{pmatrix} \quad (1)$$

$$\cos \Delta\phi_c = \frac{1}{2} (a + d) = \frac{1}{2} \operatorname{Tr} M$$

IN DISCUSSION OF STABILITY CRITERION
IN FODO

$$-1 \leq \frac{1}{2} \operatorname{Tr} M \leq 1 \rightarrow -1 \leq \cos \mu \leq 1$$

COMPARING μ IN $e^{i\mu}$ IS $\Delta\phi_c$

→ PHASE ADVANCE THROUGH REPEAT PERIOD.

FROM ① ON LAST PAGE

$$\beta = \frac{b}{\sin \Delta \phi_c} ; \alpha = \frac{a-d}{2 \sin \Delta \phi_c}$$

$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ IS TRANSFER MATRIX
AT THIS POINT IN LATTICE

IF ONE KNOWS M CAN GET α, β
WHICH ALLOW ONE TO CALCULATE
PARTICLE MOTION

EQ M COULD BE

$$\begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix} \text{ OR } \begin{pmatrix} \cos \sqrt{K}L & \frac{1}{\sqrt{K}} \sin(KL) \\ -\sqrt{K} \sin(KL) & \cos \sqrt{K}L \end{pmatrix} \text{ OR etc...}$$

DRIFT FOCUSING QUAD

IF ONE DETERMINES β AT EVERY POINT
ON LATTICE, MOTION FROM $1 \rightarrow 2$.

$$\begin{pmatrix} x \\ x' \end{pmatrix}_{S_2} = M(S_1 \rightarrow S_2) \begin{pmatrix} x \\ x' \end{pmatrix}_{S_1}$$

GIVE EXPLICIT FORM OF M

START WITH

$$x = \omega(s)(A_1 \cos \phi + A_2 \sin \phi)$$

$$x' = \left(A_1 \omega'(s) + \frac{A_2}{\omega} \right) \cos \phi + \left(A_2 \omega'(s) - \frac{A_1}{\omega(s)} \right) \sin \phi$$

INITIAL CONDITIONS $x_1, x'_1, s = s_1$

$$\rightarrow A_1 = \frac{x'_1}{\omega_1}; \quad A_2 = x'_1 \omega_1 - x_1 \omega'_1 \quad \}$$

$$\omega_1 = \sqrt{\beta}, \quad \text{AND} \quad \alpha_1 = -\frac{\beta_1'}{2}$$

$$x_2 = \sqrt{\frac{\beta_2}{\beta_1}} (\cos \Delta\phi_c + \alpha_1 \sin \Delta\phi_c) \cdot x_1 + \sqrt{\beta_1 \beta_2} \sin \Delta\phi_c \cdot x_1'$$

$$x_2' = - \left\{ \frac{1 + \alpha_1 \alpha_2}{\sqrt{\beta_1 \beta_2}} \sin \Delta\phi_c + \frac{\alpha_1 - \alpha_2}{\sqrt{\beta_1 \beta_2}} \cos \Delta\phi_c \right\} \cdot x_1 + \sqrt{\frac{\beta_1}{\beta_2}} (\cos \Delta\phi_c - \alpha_2 \sin \Delta\phi_c) \cdot x_1'$$

$$M = \begin{pmatrix} \left(\frac{\beta_2}{\beta_1}\right)^{1/2} (\cos \Delta\phi_c + \alpha_1 \sin \Delta\phi_c) & \left(\beta_1 \beta_2\right)^{1/2} \sin \Delta\phi_c \\ -\frac{1 + \alpha_1 \alpha_2}{\left(\beta_1 \beta_2\right)^{1/2}} \sin \Delta\phi_c + \frac{\alpha_1 - \alpha_2}{\left(\beta_1 \beta_2\right)^{1/2}} \cos \Delta\phi_c & \left(\frac{\beta_1}{\beta_2}\right)^{1/2} (\cos \Delta\phi_c - \alpha_2 \sin \Delta\phi_c) \end{pmatrix}$$

$$\Delta\phi_c = \int_{s_1}^{s_2} \frac{ds}{\beta(s)}$$